

# Lecture №8: Quasi-periodicity, 3-D and higher order systems, introduction to chaos, chaotic water wheel, the Lorenz attractor, *coursework requirements*

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# Lecture outline

- Quasi-periodicity in 2-D and 3-D systems, trajectories on the surface of a torus
- 3-D systems and higher order systems
- What is chaos? Deterministic chaos, chaos theory, definition of chaos
- Examples of *chaotic* systems:
  - Chaotic water wheel, the Lorenz mill
  - The Lorenz attractor
- A remark on plotting 3-D phase portraits
- *Coursework requirements*



Let's consider a system<sup>1</sup> given in the following form:

$$\begin{cases} \dot{\theta}_1 = \omega_1 + K_1 \sin(\theta_2 - \theta_1), \\ \dot{\theta}_2 = \omega_2 + K_2 \sin(\theta_1 - \theta_2), \end{cases} \quad (1)$$

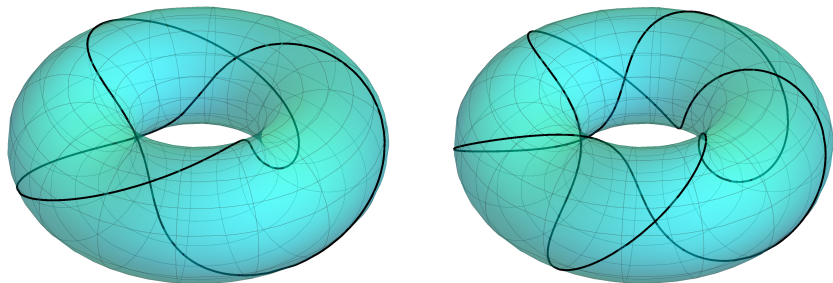
where  $\theta_1$  and  $\theta_2$  are the angular displacements,  $\omega_1$  and  $\omega_2$  are the natural frequencies, and  $K_1$  and  $K_2$  are the coupling constants. Solution trajectories of Sys. (1) are studied on the surface of a torus.

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<sup>1</sup>See Mathematica .nb file uploaded to the course website.

# Quasi-periodicity<sup>2</sup>

Transitioning from 2-D to 3-D systems.



**Figure:** Two examples of closed trajectories defined by Sys. (1) as they appear on the surfaces of tori. (Left) Trefoil knot ( $p = 3$ ,  $q = 2$ ). (Right) Cinquefoil knot ( $p = 5$ ,  $q = 2$ ).

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<sup>2</sup>See Mathematica .nb file uploaded to the course website.

# Chaos, dictionary definition

**Chaos**<sup>3</sup> in day-to-day laymen jargon (colloquial meaning):

- a state of utter confusion or disorder.
- a total lack of organisation or order.
- complete confusion and disorder; *a state in which behaviour and events are not controlled by anything.*
- a state of things in which chance is supreme; *especially, the confused unorganised state of primordial matter before the creation of distinct forms.*
- any confused, disorderly mass: *a chaos of meaningless phrases.*

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<sup>3</sup>Source: various online dictionaries.

# Chaos in mathematics and physics

**Chaos theory** is the field of study in mathematics that studies the behaviour of dynamical systems that are *highly* sensitive to initial conditions – a response popularly referred to as the “**butterfly effect**”. Small differences in initial conditions (such as those due to rounding errors in numerical computation or measurement uncertainty) yield widely diverging outcomes for such dynamical systems, rendering long-term prediction impossible in general. This happens even though these systems are *deterministic*, meaning that their future behaviour is fully determined by their initial conditions, with no random (stochastic) elements involved. In other words, the *deterministic nature* of these systems does not make them *predictable*. This behaviour is known as **deterministic chaos**, or simply **chaos**. Chaotic behaviour exists in many natural systems, such as weather and climate. It also occurs spontaneously in some systems with artificial components, such as road traffic.

# Chaos in mathematics and physics

The fact that deterministic system is not predictable (determined) in *practice* is not an internally contradicting statement, its a manifestation of a **new mathematical property or type of solution** of higher order (order more than two) nonlinear systems, called **chaos**. Also, this long-term **aperiodic** solution is qualitatively different from the periodic and quasi-periodic solutions since solutions with slightly different initial conditions deviate exponentially.

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The **chaos** was summarised by Edward Lorenz as:  
*Chaos – when the present determines the future, but the approximate present does not approximately determine the future.*

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When predicting *distant* future states of a chaotic system one can never know the starting point accurately enough.

# Chaos in mathematics and physics

The **chaos theory** explains deterministic systems which in principle can be predicted, for a time, then appear to become random. The amount of time patterns can be predicted depends on a time scale (the Lyapunov time) determined by the system's dynamics.

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Chaos is a property of reality that we sense when we try to predict *distant* future.

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**SRB measure** (Sinai-Ruelle-Bowen measure) – If statistics of trajectories of a system are **insensitive** to initial conditions or small differences of initial conditions then we say that the system has a SRB measure.

# Chaotic systems: The Lorenz mill<sup>4</sup>

Equations of motion of a chaotic water wheel a.k.a. the **Lorenz mill** are the following:

$$\begin{cases} \dot{a}_1 = \omega b_1 - K a_1, \\ \dot{b}_1 = -\omega a_1 - K b_1 + q_1, \\ \dot{\omega} = -\frac{\nu}{I} \omega + \frac{\pi G r}{I} a_1, \end{cases} \quad (2)$$

where  $I$  is the moment of inertia,  $\theta$  is the angle of the wheel,  $\omega$  is the angular velocity,  $K$  is the liquid's leakage rate,  $\nu$  is the damping rate,  $r$  is the radius of the wheel,  $G$  is the effective gravity constant.  $a_1$  and  $b_1$  are the Fourier amplitudes of the first modes of the liquid's mass distribution function

$$m(\theta, t) = \sum_{n=0}^{\infty} a_n(t) \sin n\theta + b_n(t) \cos n\theta. \quad (3)$$

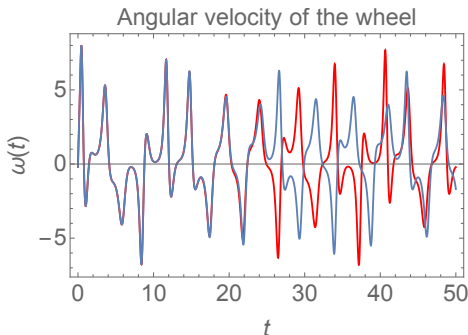
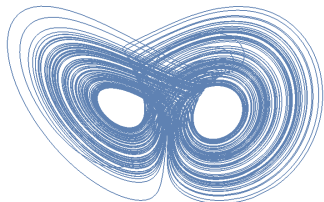
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<sup>4</sup>See Mathematica .nb file uploaded to the course website.

# Chaotic systems: The Lorenz mill

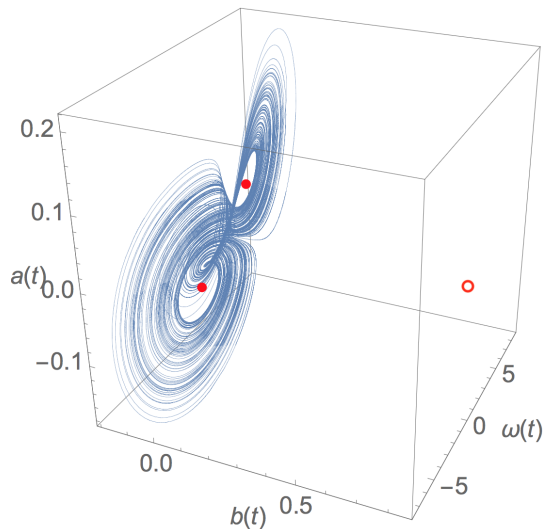
And,  $g_1$  is the Fourier amplitude of the first mode of the liquid inflow mass distribution function

$$Q(\theta) = \sum_{n=0}^{\infty} q_n \cos n\theta. \quad (4)$$



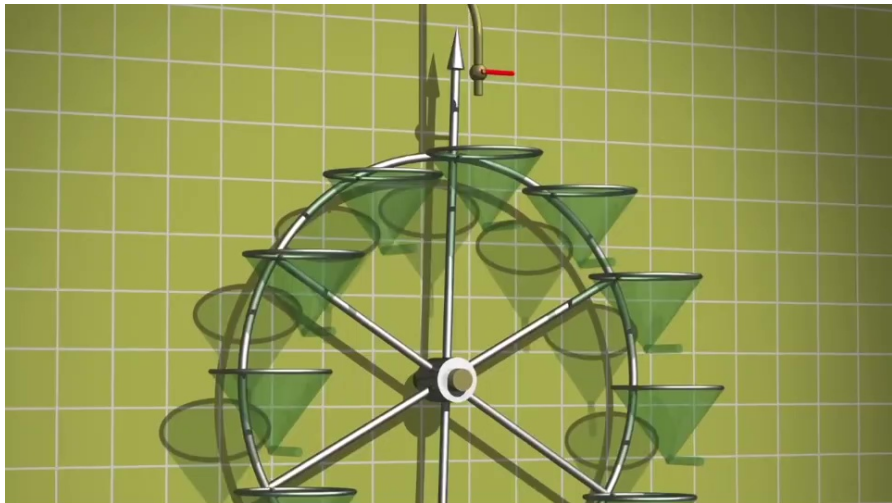


# Chaotic systems: The Lorenz mill<sup>5</sup>



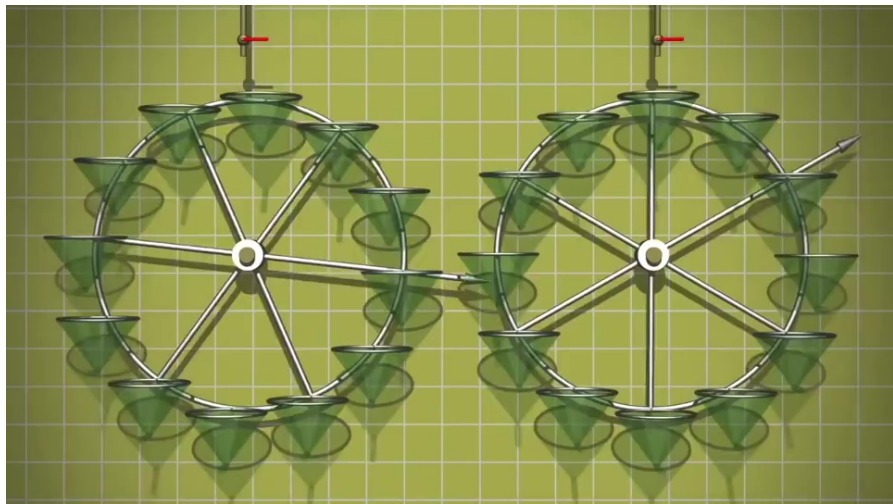
<sup>5</sup>See Mathematica .nb file uploaded to the course website.

# Chaotic systems: The Lorenz mill and chaos



Credit: CC-BY: Jos Leys, Étienne Ghys, Aurélien Alvarez, <http://www.chaos-math.org/>

# Chaotic systems: The Lorenz mill, SRB measure



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# Chaotic systems: The Lorenz attractor

The **Lorenz attractor**:<sup>6</sup> It can be shown that Sys. (2) is a specific case of a more general system in the form:

$$\begin{cases} \dot{x} = \sigma(y - x), \\ \dot{y} = rx - y - xz, \\ \dot{z} = xy - bz, \end{cases} \quad (5)$$

where  $\sigma, r, b > 0$  are the control parameters.

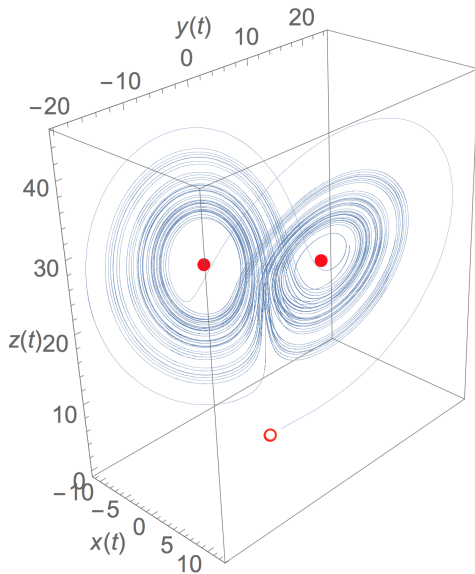
**Read:** E. N. Lorenz, "Deterministic nonperiodic flow". *Journal of the Atmospheric Sciences*, **20**(2), pp. 130–141 (1963).

[http://dx.doi.org/10.1175/1520-0469\(1963\)020<0130:DNF>2.0.CO;2](http://dx.doi.org/10.1175/1520-0469(1963)020<0130:DNF>2.0.CO;2)

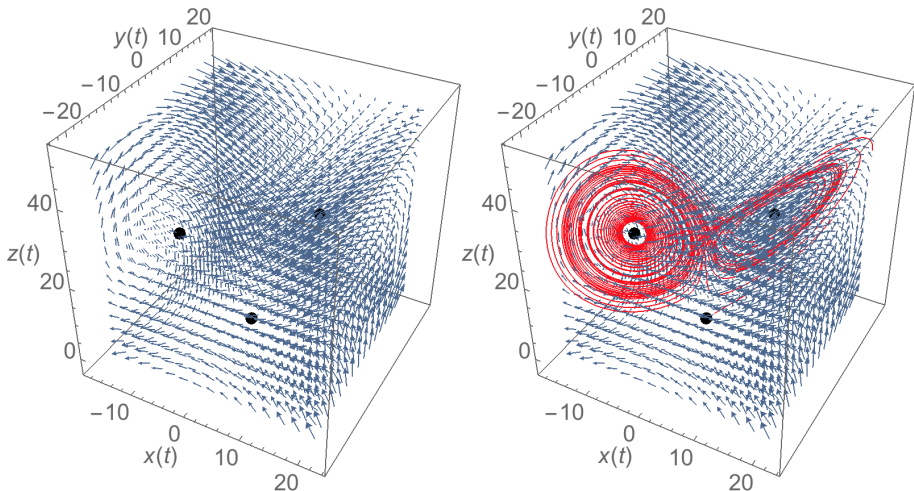
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<sup>6</sup>See Mathematica .nb file uploaded to the course website.

# Chaotic systems: The Lorenz attractor

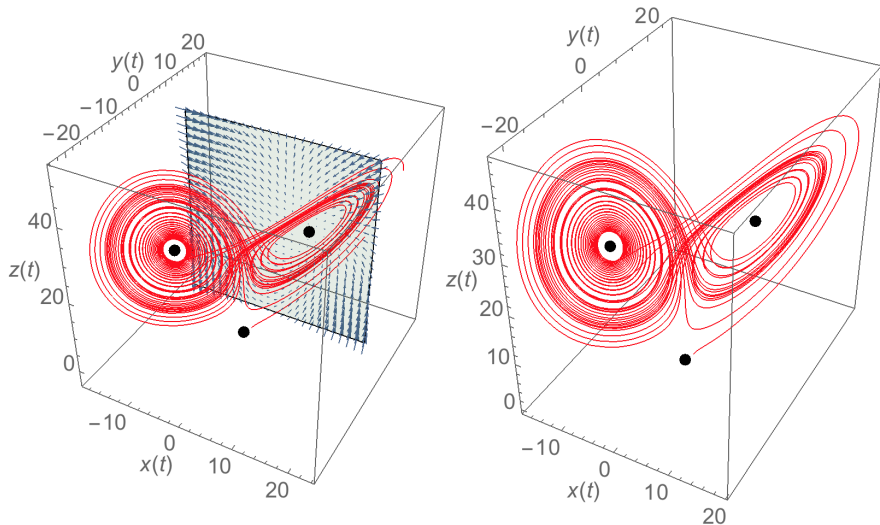


# A remark on 3-D phase portrait visualisation<sup>7</sup>



<sup>7</sup>See Mathematica .nb file uploaded to the course website.

# A remark on 3-D phase portrait visualisation



# Conclusions

- Quasi-periodicity
- Chaos, deterministic chaos, chaos theory
- Examples of chaotic systems:
  - Chaotic water wheel, the Lorenz mill
  - The Lorenz attractor
- A remark on plotting 3-D phase portraits
- *Coursework requirements*



# Revision questions

- What is quasi-periodicity?
- Can quasi-periodic system generate a chaotic solution? Why?
- Do limit-cycles exist in 3-D phase spaces? Sketch an example.
- What are 3-D and higher order systems?
- What is chaos in the context of dynamical systems (deterministic chaos, chaos theory)?
- Name properties of chaotic systems.
- What does it mean that a chaotic system has a SRB measure (Sinai-Ruelle-Bowen measure)?
- What is chaotic water wheel?
- What is the Lorenz attractor?