Lecture №15: Overview of the course, concluding remarks and summary, *exam*

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- Comments on your coursework evaluation results
- Overview of the course
- Highlights

• Exam, what to expect?

Intro to theory: basic definitions (from Lecture $N_{2}1$)

Mechanics (solid and fluid) can be roughly divided into **statics** and **dynamics**.

• **Statics:** the branch of mechanics concerned with the forces acting on stationary bodies. The acting forces are in equilibrium.

• **Dynamics:** the branch of mechanics concerned with the *motion*/changes of *bodies*/systems under the action of forces. The acting forces are not in equilibrium.

The branch of any science in which changes in variables are considered e.g. chemical kinetics, population biology, nonlinear oscillations, econophysics, etc. All these subjects can be placed under a common mathematical framework.

Nonlinear dynamics: concerns with dynamical systems or processes that are inherently *nonlinear*. Nonlinear dynamical systems, describing changes in variables over time, may appear *chaotic*, *unpredictable*, or *counterintuitive*, contrasting with much simpler linear systems.

Introduction, roadmap (from Lecture Nº1)

- 1-D systems (homogeneous ODEs)
- 2-D systems
 - Classification of fixed points (linear systems)
 - Classification of bifurcations
- Quasi-periodisity.
- 3-D systems and higher order systems
 - Strange attractors and chaos
 - Fractal geometry
 - Fractal microstructure of strange attractors
- Poincaré map
- 1-D maps and period doubling
- 2-D maps
 - Classification of fixed points (linear maps)
- Higher dimensional maps and complex valued maps

The course can be divided into **six main milestones** and one overall conclusion:

- Fundamentals of the course
- Olassification of fixed points and bifurcations
- Periodicity, quasi-periodicity and aperiodicity
- Chaos and three-dimensional systems
- S Analysis of chaos, long-term behaviour
- Connection between nonlinear dynamical systems and the Mandelbrot set, and the Fatou and Julia sets

1 Fundamentals of the course.



1-D flow problems and impossibility of oscillations in 1-D systems.

1 Fundamentals of the course.



2-D systems and 2-D phase portraits.

1 Fundamentals of the course.



The Poincaré–Bendixson theorem and limit-cycles in continuous-time systems.

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⁽²⁾ Classification of fixed points and bifurcations



Figure: Classification of fixed points in 2-D linear systems.

⁽²⁾ Classification of fixed points and bifurcations



Figure: Classification of fixed points in 2-D linear maps.

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② Classification of fixed points and bifurcations



Figure: Classification of bifurcations and the Hopf bifurcation.

② Classification of fixed points and bifurcations



Figure: Classification of bifurcations and Hopf bifurcation.

③ Periodicity, quasi-periodicity and aperiodicity



Figure: A closed trajectory on the surface of the torus. Toroidal knot.

Transitioning from 2-D to 3-D systems.

(4) Chaos and 3-D systems (higher order systems)



- Predictability horizon or the Lyapunov time
- The Lyapunov exponents
- The Kolmogorov entropy
- Chaotic or strange attractor

(4) Chaos and 3-D systems (higher order systems)



(4) Chaos and 3-D systems (higher order systems)



Number of layers in a real attractor $2^{\infty} = \infty$.

Fractal microstructure of strange attractors. The stretching-folding-re-injection dynamics.

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Overview of the course: Taffy pulling



Overview of the course: Coffee and cream



Overview of the course: Air plume



Overview of the course: Air



Overview of the course: Ash cloud



Overview of the course: Atmosphere





Figure: Jupiter. From left to right: the sequence of images taken on Sept. 1, 2017. At the time the images were taken, the spacecraft ranged from 12 143 to 22 908 km from the tops of the clouds of the planet. Credit: NASA/JPL-Caltech/SwRI/MSSS/Gerald Eichstädt/Seán Doran

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Figure: Left: Image acquired on May 19, 2017, from an altitude of about 33 400 km above Jupiter's cloud tops. Right: Image captured, from an altitude of 18 906 km.

Credit: NASA/JPL-Caltech/SwRI/MSSS/Gerald Eichstädt/Seán Doran

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Figure: Kalliroscope.

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(4) Chaos and 3-D systems (higher order systems)



Figure: Local fractal microstructure of strange attractors. The Poincaré section and internal structure of the Lorenz section.

(5) Analysis of chaos, long-term behaviour. The Poincaré mapping of higher order systems.

3-D attractor



Construction of the Poincaré map $\vec{P}(\vec{x}') = (f_1(x', y'), f_2(x', y'))^T$ (1). Mapping of the Poincaré section points where r is the radial distance from the origin ("flat" attractor).

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⁽⁵⁾ Analysis of chaos, long-term behaviour.



The Feigenbaum constants α , δ and the universal limiting functions – **universal route to chaos** via a cascade of period doubling bifurcations.

(6) Connection between nonlinear dynamical systems and the Mandelbrot set, and the corresponding Fatou and Julia sets.



Parameter space and stable period-p cycles (polynomial space) State spaces, initial conditions leading to all stable period-p orbits (basins of stable solutions)

Overview of the course, main conclusions

Be knowledgeable when dealing with nonlinearity!



Figure: Nonlinear and linear systems.

Overview of the course, main conclusions

Be knowledgeable/careful when dealing with nonlinearity, especially when dealing with bifurcating nonlinear systems, systems in chaotic regime or systems with strange attractors. Keep in mind the predictability horizon and the Lyapunov exponents.



Figure: Comparison of linear and higher order nonlinear systems.

Overview of the course, main conclusions

Be knowledgeable/careful when dealing with nonlinearity, especially when dealing with bifurcating nonlinear systems, systems in chaotic regime or systems with strange attractors. Keep in mind the predictability horizon and the Lyapunov exponents.



Don't fuck with nonlinearity!

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A practice mock exam is added to the lecture notes (Lecture 15) and the course webpage.

The final exam consist of:

- Three *simple* questions or definitions (12 points each) selected from the pool of the revision questions (non verbatim)
- Three simple math problems (for 12 or 13 points each)
- **Two video questions** (13 points each) designed to test your reasoning ability

Maximum points: 100. The exam is graded according to the TalTech grading scale.

Exam, an example video



Figure: Magnetic pendulum in three magnetic potentials.

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Exam, an example video



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• Next: Exam

Reminder: The positively graded coursework is a prerequisite for taking the exam!