# Lecture №2: 1-D problems, linear analysis, bifurcation, bifurcation diagram

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### Lecture outline

- $\bullet\,$  Linearisation about a fixed point  $x^*$
- $\bullet\,$  Linear stability analysis of fixed point  $x^*$
- Existence and uniqueness of solutions of 1-D systems
- Impossibility of oscillations in 1-D systems
- Bifurcation
- Bifurcation point (value of parameter)
- Saddle-node bifurcation. Ex:  $\dot{x} = r \pm x^2$ Ex:  $\dot{x} = r + x - \ln(1 + x)$
- Bifurcation diagram
- Normal form
- Transcritical bifurcation. Ex:  $\dot{x} = rx \pm x^2 = x(r \pm x)$ .
- Pitchfork bifurcation. Ex:  $\dot{x} = rx \pm x^3$ .
- Supercritical ( $\dot{x} = rx x^3$ ) and subcritical ( $\dot{x} = rx + x^3$ ) pitchfork bifurcations

# Linearisation of 1-D systems

The one-dimensional system is given by

$$\dot{x} = f(x). \tag{1}$$

The dynamics close to fixed point  $x^*$  can be expressed as follows

$$x(t) = x^* + \eta(t), \tag{2}$$

where  $|\eta| \ll 1$  is a small perturbation. The behaviour and change of solution x over time thus is

$$\dot{x} = (x^* + \eta) = \dot{\eta}. \tag{3}$$

At the same time (1) holds. This mans that the dynamics of small perturbations is the following

$$\dot{\eta} = f(x) = f(x^* + \eta).$$
 (4)

# Linearisation of 1-D systems

Taylor series expansion about  $x^*$  of (4) results in

$$\begin{split} \dot{\eta} &= f(x) = f(x^* + \eta) \tag{5} \\ &= f(x^*) + \frac{f'(x^*)}{1!}(x^* + \eta - x^*) + \frac{f''(x^*)}{2!}(x^* + \eta - x^*)^2 + \dots \tag{6} \\ &= f'(x^*)\eta + \underbrace{\frac{f''(x^*)}{2!}\eta^2 + \dots}_{\text{higher order terms, } O(\eta^2)} \tag{7} \\ &\approx f'(x^*)\eta. \end{aligned}$$

If  $f'(x^*) \neq 0$ , then the term  $|f'(x^*)\eta| \gg \left|\frac{f''(x^*)}{2!}\eta^2\right|$ . Neglecting  $O(\eta^2)$  yields the linearisation of the system about fixed point  $x^*$ 

$$\dot{\eta} = s\eta,$$
 (9)

where  $s = f'(x^*)$  is simply the slope of function f(x) evaluated at  $x^*$ .

# Algebraic decay



Figure: Algebraic decay near a fixed point: A family of numerical solutions of  $\dot{x} = -x^3$ . The initial condition of the solution shown with the red curve is x(0) = 1. An algebraic decay path  $x(t) \sim t^{-\delta}$ , where  $\delta$  is constant, is shown with the blue curve.

# Existence and uniqueness



**Existence and uniqueness:** Solutions to  $\dot{x} = f(x)$  exist and they are unique if f(x) and f'(x) are continuous, i.e, the function f is continuously differentiable.

# Bifurcation

**Bifurcation:** The term is related to models with instabilities, sudden changes and transitions.



With the change of a parameter the qualitative structure of the *vector field* may change dramatically — fixed points may be <u>created</u> or <u>destroyed</u>, or they might <u>change their stability</u>. Such a change is called **bifurcation**.

**Bifurcation point** is the value of the parameter at witch the sudden change (bifurcation) occurs.

**Bifurcation coordinate** is the coordinate (free variable) at witch the bifurcation occurs.

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# Conclusions

- $\bullet\,$  Linearisation about a fixed point  $x^*$
- Linear stability analysis of fixed point  $\boldsymbol{x}^*$
- Bifurcation
- Bifurcation diagram
- Saddle-node bifurcation
- Transcritical bifurcation
- Pitchfork bifurcation (subcritical, supercritical)

### Revision questions

- What does linearisation of a nonlinear system imply?
- Linearise the following 1-D system

$$\dot{x} = x^3 - x \tag{10}$$

- What is bifurcation?
- What is bifurcation diagram?
- What is saddle-node bifurcation?
- What is transcritical bifurcation?
- What is pitchfork bifurcation?
- What is supercritical pitchfork bifurcation?
- What is subcritical pitchfork bifurcation?
- What is normal form in the context of bifurcations?
- Are oscillation possible in 1-D systems?
- Why are oscillations impossible in 1-D systems?
- What does uniqueness of solutions imply in the context of phase space trajectories?

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